

Note on a Randomized Krylov Subspace Method

Jonas Bresch*

Technische Universität Berlin

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The Krylov subspace for a matrix $A \in \mathbb{R}^{n \times n}$ and vector $b \in \mathbb{R}$ is given by

$$\mathcal{K}_k(A, b) := \text{span}\{b, Ab, A^2b, \dots, A^{k-1}b\}. \quad (1)$$

The concept is named after Russian applied mathematician and naval engineer ALEXEI KRYLOV, who published a paper about the concept in 1931 [7].

Here, we will consider to solve the optimization problem [4]

$$\min_{x \in \mathbb{R}^n} \|Ax - b\|_2^2 \quad (2)$$

known as the least square problem via the at most k -dimensional KRYLOV subspaces $\mathcal{K}_k(A, b)$. This means, we aim to solve [7]

$$x^k \in \arg \min_{x \in \mathcal{K}_k(A, b)} \|Ax - b\|_2^2. \quad (3)$$

As a first note, we observe that the solution in the k th iteration is precisely given by solving a system of linear equations for the coordinates with respect to the KRYLOV subspaces $\mathcal{K}_k(A, b)$, cf. (1), iteratively. Later one, we aim to solve (3) by a random optimization method similar, but different to [9]. This is inspired by [1–3] as well as [6; 8] for the eigenvalue problem and [5; 9; 10] for the randomized methods.

Therefore, let us denote the vectors of the inducing system for the KRYLOV subspace (1) by

$$b^0 := b, \quad b^\ell := Ab^{\ell-1}, \quad \ell \in \{1, \dots, k-1\},$$

so that

$$b^\ell = Ab^{\ell-1} = AAb^{\ell-2} = A^2b^{\ell-2} = A^\ell b^0 = A^\ell b.$$

Then for solving (3) we rewrite the variables x in the coordinates of the inducing system of (1), i.e.

$$x = \sum_{\ell=0}^{k-1} \gamma_\ell b^\ell \in \mathcal{K}_k(A, b), \quad \gamma_\ell \in \mathbb{R}, \quad \ell \in \{0, \dots, k-1\}. \quad (4)$$

We further define the variables

$$\beta_{i,j} := \langle b^i, b^j \rangle, \quad (i, j) \in \{1, \dots, k\} \times \{0, \dots, k\}.$$

*Webpage and Email
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Plugging in (4) in the objective from (3) yields

$$\begin{aligned}
\|Ax - b\|_2^2 &= \|Ax\|_2^2 - 2\langle Ax, b \rangle + \text{const.} \\
&= \left\| A \left(\sum_{\ell=0}^{k-1} \gamma_\ell b^\ell \right) \right\|_2^2 - 2 \left\langle A \left(\sum_{\ell=0}^{k-1} \gamma_\ell b^\ell \right), b \right\rangle + \text{const.} \\
&= \left\| \sum_{\ell=0}^{k-1} \gamma_\ell A b^\ell \right\|_2^2 - 2 \left\langle \sum_{\ell=0}^{k-1} \gamma_\ell A b^\ell, b \right\rangle + \text{const.} \\
&= \left\| \sum_{\ell=0}^{k-1} \gamma_\ell b^{\ell+1} \right\|_2^2 - 2 \left\langle \sum_{\ell=0}^{k-1} \gamma_\ell b^{\ell+1}, b \right\rangle + \text{const.} \\
&= \sum_{i,j=0}^{k-1} \gamma_i \gamma_j \langle b^{i+1}, b^{j+1} \rangle - 2 \sum_{i=0}^{k-1} \gamma_i \langle b^{i+1}, b^0 \rangle + \text{const.} \\
&= \sum_{i,j=0}^{k-1} \gamma_i \gamma_j \beta_{i+1,j+1} - 2 \sum_{i=0}^{k-1} \gamma_i \beta_{i+1,0} + \text{const.} \\
&= \sum_{i=0}^{k-1} \gamma_i^2 \beta_{i+1,i+1} + 2 \sum_{0 \leq i < j \leq k-1} \gamma_i \gamma_j \beta_{i+1,j+1} - 2 \sum_{i=0}^{k-1} \gamma_i \beta_{i+1,0} + \text{const.}
\end{aligned}$$

Hence, the necessary optimality conditions are given by

$$\begin{aligned}
\partial_{\gamma_i} \|Ax - b\|_2^2 &= 0 \\
\Leftrightarrow \quad 0 &= 2\gamma_i \beta_{i+1,i+1} + 2 \sum_{j \neq i} \gamma_j \beta_{i+1,j+1} - 2\beta_{i+1,0} \\
\Leftrightarrow \quad 0 &= 2 \left(\sum_{j=0}^{k-1} \gamma_j \beta_{i+1,j+1} - \beta_{i+1,0} \right), \quad i \in \{0, \dots, k-1\}. \tag{5}
\end{aligned}$$

If we set

$$B := [\beta_{i+1,j+1}]_{i,j=0}^{k-1} \in \mathbb{R}^{k \times k}, \quad \gamma = (\gamma_0, \dots, \gamma_{k-1})^\top, \quad \beta_0 := (\beta_{1,0}, \dots, \beta_{k,0})^\top \in \mathbb{R}^k,$$

then we obtain (5) as a system of linear k linear equation in k variables:

$$B\gamma = \beta_0. \tag{6}$$

Then the solution γ^* may defines the solution $x^k = \sum_{\ell=0}^{k-1} \gamma_\ell^* b^\ell$. If B is invertible, i.e. the inducing system $\{b^1, \dots, b^k\} = A\{b^0, \dots, b^{k-1}\}$ from (1) is a basis, then the solution is unique.

Now, to avoid solving (6) we propose to solve instead iteratively a fairly simple update scheme for solving the minimization problem (3) in the k th instance. Therefore, we aim to choose as random update direction w_k where the coefficients within the inducing system $\{b^0, \dots, b^{k-1}\}$ from (1) are standard normal distributed, i.e. let

$$w_t^k = \sum_{\ell=0}^{k-1} \eta_\ell b^\ell, \quad \eta_\ell \sim \mathcal{N}(0, 1), \quad \text{iid.} \quad \ell \in \{0, \dots, k-1\}.$$

Then for some appropriate step size $\tau \in \mathbb{R}$ we can define the next iterate

$$x_{t+1}^k = x_t^k + \tau w_t^k = \sum_{\ell=0}^{k-1} \gamma_t^\ell b^\ell + \tau \sum_{\ell=0}^{k-1} \eta_t^\ell b^\ell = \sum_{\ell=0}^{k-1} (\gamma_t^\ell + \tau \eta_t^\ell) b^\ell, \quad (7)$$

where we choose for $t = 0$ the initial coefficients for x_0^k standard normal, too, in (1). Hence, we just update the coefficients by the “optimal” step size $\tau \in \mathbb{R}$ we have to determine. Therefore, we consider (7) in the objective rom (3) which yields

$$\begin{aligned} \|Ax_{t+1}^k - b\|_2^2 &= \|A(x_t^k + \tau w_t^k) - b\|_2^2 \\ &= \|A(x_t^k + \tau w_t^k)\|_2^2 - 2\langle A(x_t^k + \tau w_t^k), b \rangle + \text{const.} \\ &= 2\tau \langle Ax_t^k, Aw_t^k \rangle + \tau^2 \|Aw_t^k\|_2^2 - 2\tau \langle Aw_t^k, b \rangle + \text{const.} \end{aligned}$$

with necessary optimality criteria

$$\begin{aligned} \partial_\tau \|Ax_{t+1}^k - b\|_2^2 &= 0 \\ \Leftrightarrow 0 &= \langle Ax_t^k, Aw_t^k \rangle + \tau \|Aw_t^k\|_2^2 - \langle Aw_t^k, b \rangle \\ \Leftrightarrow \tau &= \frac{\langle Aw_t^k, b \rangle - \langle Ax_t^k, Aw_t^k \rangle}{\|Aw_t^k\|_2^2} \\ \Leftrightarrow \tau &= \langle Aw_t^k, b - Ax_t^k \rangle \|Aw_t^k\|_2^{-2} \end{aligned}$$

and by the second derivative, which is $\partial_\tau^2 \|Ax_{t+1}^k - b\|_2^2 = 2\|Aw_t^k\|_2^2 \geq 0$, yields the minimizer. As we can express

$$Aw_t^k = A\left(\sum_{\ell=0}^{k-1} \eta_t^\ell b^\ell\right) = \sum_{\ell=0}^{k-1} \eta_t^\ell Ab^\ell = \sum_{\ell=0}^{k-1} \eta_t^\ell b^{\ell+1}$$

as well as

$$Ax_t^k = A\left(\sum_{\ell=0}^{k-1} \gamma_t^\ell b^\ell\right) = \sum_{\ell=0}^{k-1} \gamma_t^\ell Ab^\ell = \sum_{\ell=0}^{k-1} \gamma_t^\ell b^{\ell+1}$$

it holds

$$\begin{aligned} \langle Aw_t^k, b - Ax_t^k \rangle &= \left\langle \sum_{\ell=0}^{k-1} \eta_t^\ell b^{\ell+1}, b - \sum_{\ell=0}^{k-1} \gamma_t^\ell b^{\ell+1} \right\rangle \\ &= \sum_{i=0}^{k-1} \eta_i \langle b^{i+1}, b^0 \rangle - \sum_{i,j=0}^{k-1} \eta_i \gamma_j \langle b^{i+1}, b^{j+1} \rangle \\ &= \sum_{i=0}^{k-1} \eta_i \beta_{i+1,0} - \sum_{i,j=0}^{k-1} \eta_i \gamma_j \beta_{i+1,j+1}. \end{aligned}$$

and furthermore

$$\begin{aligned} \|Aw_t^k\|_2^2 &= \left\| \sum_{\ell=0}^{k-1} \eta_t^\ell b^{\ell+1} \right\|_2^2 = \sum_{i,j=0}^{k-1} \eta_i \eta_j \langle b^{i+1}, b^{j+1} \rangle \\ &= \sum_{i,j=0}^{k-1} \eta_i \eta_j \beta_{i+1,j+1} = \sum_{i=0}^{k-1} \eta_i \beta_{i+1,i+1} + 2 \sum_{0 \leq i < j \leq k-1} \eta_i \eta_j \beta_{i+1,j+1} \end{aligned}$$

for an efficient computation.

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